FANUC Robot CR-151A



FEATURES

FANUC Robot CR-15iA is a 15kg payload collaborative robot that can work without safety fences.

Collaborative Operation

- This robot and a human operator can work in close proximity without safety fences.
- This robot can work in cooperation with a human operator. (examples: parts assembling, workpiece transfer)
- With Hand Guidance(option), intuitive operation and easy teaching are possible.

Safety Function

- This robot stops safely when it touches a human operator.
- A human operator can move the robot by pushing it.
- This robot is certified to meet the requirements of international standard ISO 10218-1.

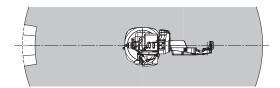
Intelligence and High Reliability

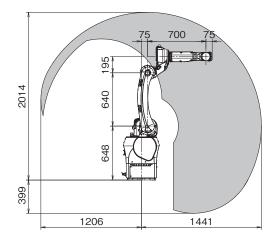
- Latest intelligent functions such as *î*RVision (Integrated vision) and force sensor are available.
- This robot is designed with the same high reliability as conventional robots.

Application Examples



CR-151A







Specifications

Model		CR-15 <i>i</i> A
Туре		6axes (J1,J2,J3,J4,J5,J6)
Reach		1441 mm
Installation		Floor, Upside-down, Angle mount
Motion range (Note 1)	J1 axis	340° / 370° 5.93 rad / 6.46 rad
	J2 axis	180° 3.14 rad
	J3 axis	312° 5.45 rad
	J4 axis	380° 6.63 rad
	J5 axis	280° 4.89 rad
	J6 axis	900° 15.71 rad
Max load capacity at wrist		15 kg
Maximum speed (Note 2)		800 mm/s (Note 3) (Max 1500 mm/s (Note 4))
Allowable load moment at wrist	J4 axis	26.0 N·m
	J5 axis	26.0 N·m
	J6 axis	11.0 N·m
Allowable load inertia at wrist	J4 axis	0.90 kg·m²
	J5 axis	0.90 kg·m²
	J6 axis	0.30 kg·m²
Repeatability(Note 5)		± 0.02 mm
Mass (Note 6)		255 kg
Installation environment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed), Short time (within one month) Max.95%RH

Note 1) In case of angle mounting, J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) It is necessary to set a motion speed according to risk assessment of system. Note 4) If the area is monitored by a safety sensor (located separately).

Note 5) Compliant with ISO9283.

Note 6) Without controller.

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