

## FANUC Robot R-2000iC



### Features

The FANUC Robot R-2000iC is an intelligent robot based on FANUC's years of experience and renowned technology. This high performance intelligent robot with outstanding reliability and cost performance will support your needs in various applications, such as spot welding, material handling and assembly.

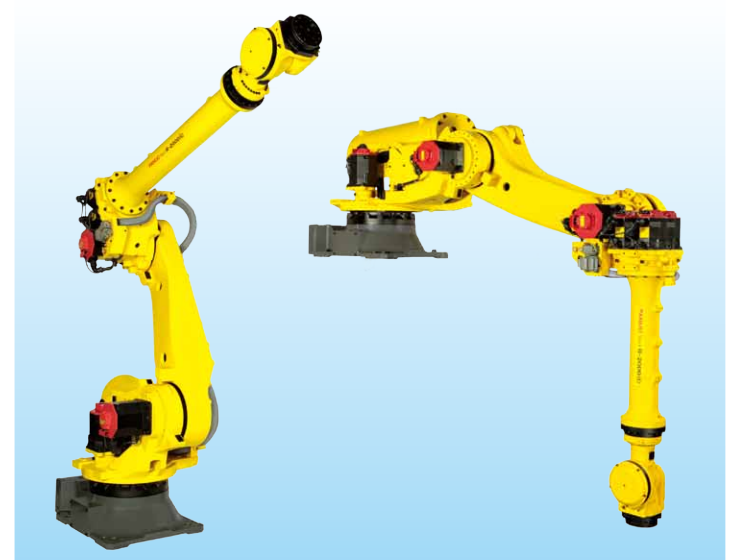
- Weight reduction of the mechanical unit and compact robot
- The rigid yet lightweight arm and the advanced motion control technology achieve significantly improved motion performance, allowing for higher productivity.
- Extensive options are available for various processes, including the spot welding solution arm.
- The R-30iB/R-30iB Plus robot controller provides energy and floor space savings with its energy regeneration option and compact cabinet.
- Available with the various intelligent features such as the Learning Robot, Bin Picking, Force Sensing and Visual Line Tracking.

### Application Example



High Speed Spot Welding

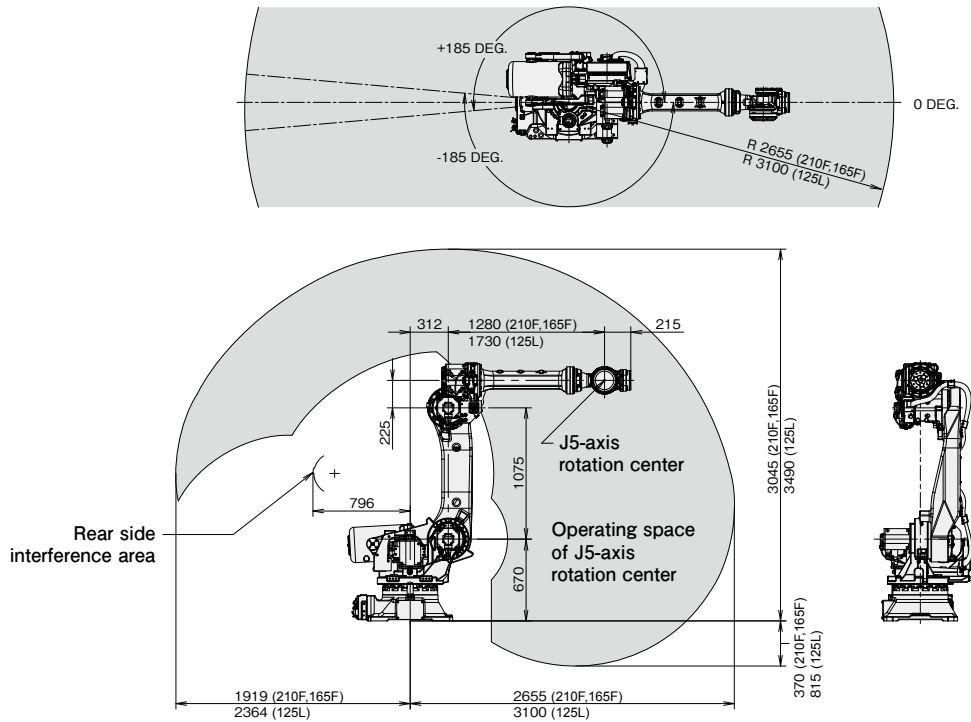
### Lineup



Long Reach/Rack Mount

## Operating space

# R-2000iC/210F,/165F,/125L



## Specifications

| Model                                      |                        | R-2000iC/210F   |                            | R-2000iC/165F        |                           | R-2000iC/125L        |                           |
|--|------------------------|---|----------------------------|----------------------|---------------------------|----------------------|---------------------------|
| Type                                       |                        | Articulated Type  |                            |                      |                           |                      |                           |
| Controlled axes                            |                        | 6 axes (J1, J2, J3, J4, J5, J6)   |                            |                      |                           |                      |                           |
| Reach                                      |                        | 2655 mm   |                            |                      |                           | 3100 mm              |                           |
| Installation                               |                        | Floor   |                            |                      |                           |                      |                           |
| Motion range<br>(Maximum speed)<br>Note 1) | J1 axis rotation       | 370°(120°/s)  | 6.46 rad (2.09 rad/s)      | 370°(130°/s)         | 6.46 rad (2.27 rad/s)     | 301°(125°/s)         | 5.25 rad (2.18 rad/s)     |
|  | J2 axis rotation       | 136°(105°/s)  | 2.37 rad (1.83 rad/s)      | 136°(115°/s)         | 2.37 rad (2.01 rad/s)     |                      |                           |
|  | J3 axis rotation       | 312°(110°/s)  | 5.45 rad (1.92 rad/s)      | 312°(125°/s)         | 5.45 rad (2.18 rad/s)     |                      |                           |
|  | J4 axis wrist rotation | 720°(140°/s)  | 12.57 rad (2.44 rad/s)     | 720°(180°/s)         | 12.57 rad (3.14 rad/s)    |                      |                           |
|  | J5 axis wrist swing    | 250°(140°/s)  | 4.36 rad (2.44 rad/s)      | 250°(180°/s)         | 4.36 rad (3.14 rad/s)     |                      |                           |
|  | J6 axis wrist rotation | 720°(220°/s)  | 12.57 rad (3.84 rad/s)     | 720°(260°/s)         | 12.57 rad (4.54 rad/s)    |                      |                           |
| Max. load capacity at wrist                |                        | 210 kg  |                            | 165 kg               |                           | 125 kg               |                           |
| Max. load capacity at J2 base              |                        | 550 kg  |                            | 550 kg               |                           | 550 kg               |                           |
| Max. load capacity on J3 arm               |                        | 25 kg (A)   | (A) + (B) ≤ 50 kg          | 25 kg (A)            | (A) + (B) ≤ 50 kg         | 25 kg (C)            | (C) + (D) ≤ 40 kg         |
| Max. load capacity on J3 casing            |                        | 50 kg (B)   |                            | 50 kg (B)            |                           | 40 kg (D)            |                           |
| Allowable load moment at wrist             | J4 axis                | 1360 N·m  | 139 kgf·m                  | 940 N·m              | 96 kgf·m                  | 710 N·m              | 72 kgf·m                  |
|  | J5 axis                | 1360 N·m  | 139 kgf·m                  | 940 N·m              | 96 kgf·m                  | 710 N·m              | 72 kgf·m                  |
|  | J6 axis                | 735 N·m   | 75 kgf·m                   | 490 N·m              | 50 kgf·m                  | 355 N·m              | 36 kgf·m                  |
| Allowable load inertia at wrist            | J4 axis                | 147 kg·m <sup>2</sup>   | 1500 kgf·cm·s <sup>2</sup> | 89 kg·m <sup>2</sup> | 908 kgf·cm·s <sup>2</sup> | 72 kg·m <sup>2</sup> | 735 kgf·cm·s <sup>2</sup> |
|  | J5 axis                | 147 kg·m <sup>2</sup>   | 1500 kgf·cm·s <sup>2</sup> | 89 kg·m <sup>2</sup> | 908 kgf·cm·s <sup>2</sup> | 72 kg·m <sup>2</sup> | 735 kgf·cm·s <sup>2</sup> |
|  | J6 axis                | 82 kg·m <sup>2</sup>  | 837 kgf·cm·s <sup>2</sup>  | 46 kg·m <sup>2</sup> | 469 kgf·cm·s <sup>2</sup> | 40 kg·m <sup>2</sup> | 408 kgf·cm·s <sup>2</sup> |
| Drive method                               |                        | Electric servo drive by AC servo motor  |                            |                      |                           |                      |                           |
| Repeatability Note 2)                      |                        | ±0.05 mm  |                            |                      |                           |                      |                           |
| Mass Note 3)                               |                        | 1090 kg   |                            | 1090 kg              |                           | 1115 kg              |                           |
| Installation environment                   |                        | Ambient temperature : 0 to 45°C<br>Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed)<br>Short term Max. 95%RH or less (within one month)<br>Vibration acceleration : 4.9m/s <sup>2</sup> (0.5G) or less |                            |                      |                           |                      |                           |

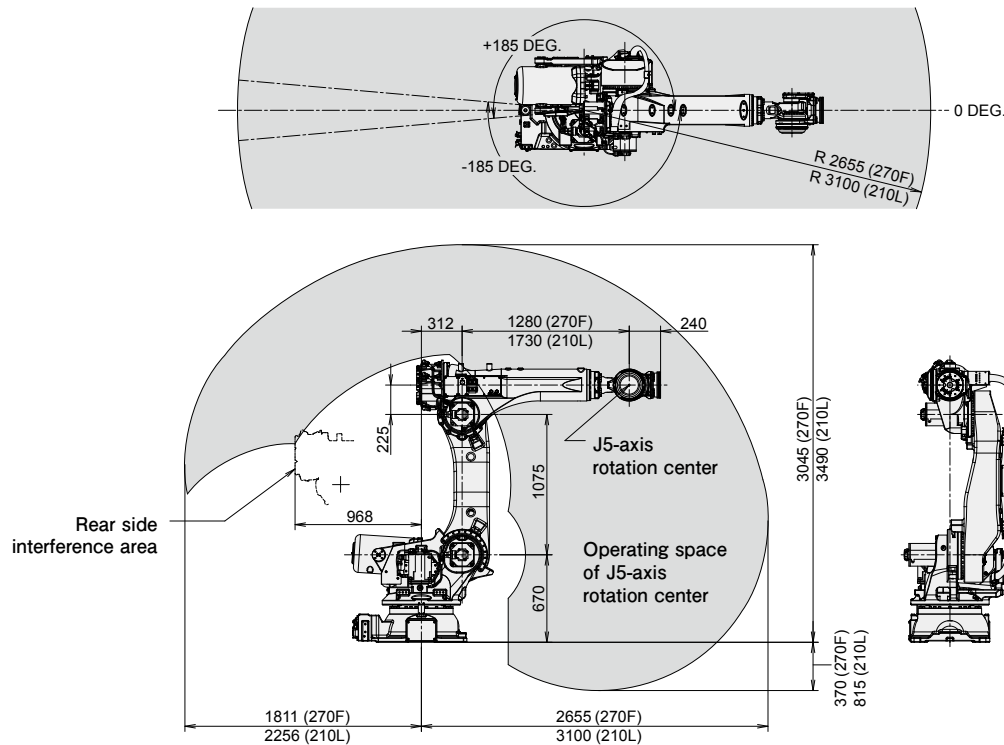
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

# Operating space

## R-2000iC/270F,/210L



## Specifications

| Model                                      |                        | R-2000iC/270F   |                       | R-2000iC/210L                                    |                       |
|--|------------------------|---|-----------------------|--|-----------------------|
| Type                                       |                        | Articulated Type  |                       |  |                       |
| Controlled axes                            |                        | 6 axes (J1, J2, J3, J4, J5, J6)   |                       |  |                       |
| Reach                                      |                        | 2655 mm   |                       | 3100 mm  |                       |
| Installation                               |                        | Floor   |                       |  |                       |
| Motion range<br>(Maximum speed)<br>Note 1) | J1 axis rotation       | 370°(105°/s) 6.46 rad (1.83 rad/s)  |                       | 370°(105°/s) 6.46 rad (1.83 rad/s)               |                       |
|  | J2 axis rotation       | 136°( 90°/s) 2.37 rad (1.57 rad/s)  |                       | 136°( 90°/s) 2.37 rad (1.57 rad/s)               |                       |
|  | J3 axis rotation       | 312°( 85°/s)  | 5.45 rad (1.48 rad/s) | 301°( 85°/s)                                     | 5.25 rad (1.48 rad/s) |
|  | J4 axis wrist rotation | 720°(120°/s) 12.57 rad (2.09 rad/s)   |                       | 720°(120°/s) 12.57 rad (2.09 rad/s)              |                       |
|  | J5 axis wrist swing    | 250°(120°/s) 4.36 rad (2.09 rad/s)  |                       | 250°(120°/s) 4.36 rad (2.09 rad/s)               |                       |
|  | J6 axis wrist rotation | 720°(200°/s) 12.57 rad (3.49 rad/s)   |                       | 720°(200°/s) 12.57 rad (3.49 rad/s)              |                       |
| Max. load capacity at wrist                |                        | 270 kg  |                       | 210 kg   |                       |
| Max. load capacity at J2 base              |                        | 550 kg  |                       | 550 kg   |                       |
| Max. load capacity on J3 arm               |                        | 40 kg (A)   | (A)×5/4+(B) ≤ 50 kg   | 20 kg (C)  | (C)×5/2+(D) ≤ 50 kg   |
| Max. load capacity on J3 casing            |                        | 50 kg (B)   |                       | 50 kg (D)  |                       |
| Allowable load moment at wrist             | J4 axis                | 1730 N·m 177 kgf·m  |                       | 1700 N·m 173 kgf·m                               |                       |
|  | J5 axis                | 1730 N·m 177 kgf·m  |                       | 1700 N·m 173 kgf·m                               |                       |
|  | J6 axis                | 900 N·m 92 kgf·m  |                       | 900 N·m 92 kgf·m                                 |                       |
| Allowable load inertia at wrist            | J4 axis                | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup>  |                       | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup> |                       |
|  | J5 axis                | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup>  |                       | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup> |                       |
|  | J6 axis                | 230 kg·m <sup>2</sup> 2347 kgf·cm·s <sup>2</sup>  |                       | 230 kg·m <sup>2</sup> 2347 kgf·cm·s <sup>2</sup> |                       |
| Drive method                               |                        | Electric servo drive by AC servo motor  |                       |  |                       |
| Repeatability Note 2)                      |                        | ±0.05 mm  |                       |  |                       |
| Mass Note 3)                               |                        | 1320 kg   |                       | 1350 kg  |                       |
| Installation environment                   |                        | Ambient temperature : 0 to 45°C<br>Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed)<br>Short term Max. 95 %RH or less (within one month)<br>Vibration acceleration : 4.9 m/s <sup>2</sup> (0.5G) or less |                       |  |                       |

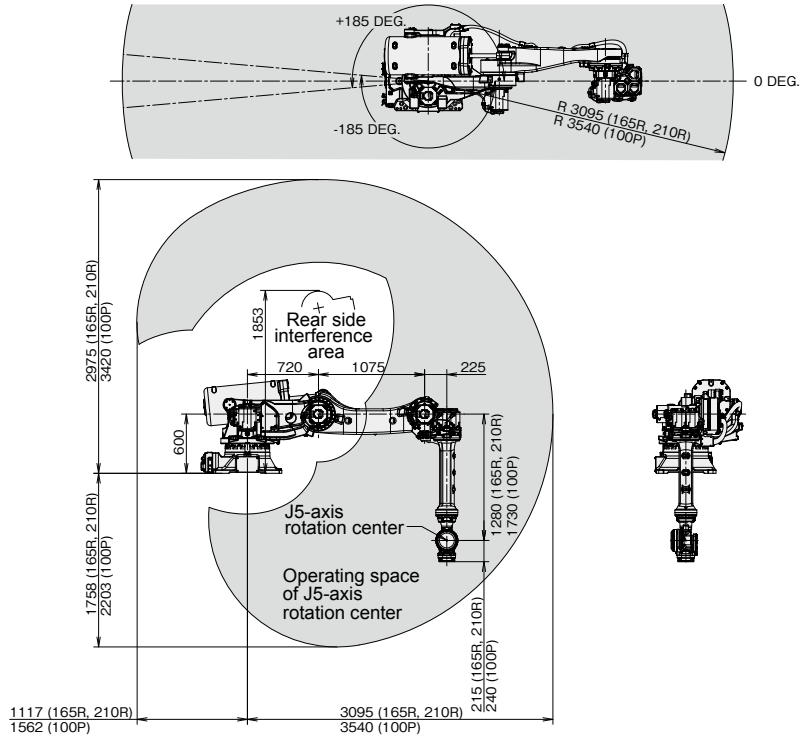
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

# Operating space

## R-2000iC/210R,/165R,/100P



# Specifications

| Model                                      |                        | R-2000iC/210R  |                            | R-2000iC/165R        |                           | R-2000iC/100P         |                            |
|--|------------------------|--|----------------------------|----------------------|---------------------------|-----------------------|----------------------------|
| Type                                       |                        | Articulated Type   |                            |                      |                           |                       |                            |
| Controlled axes                            |                        | 6 axes (J1, J2, J3, J4, J5, J6)  |                            |                      |                           |                       |                            |
| Reach                                      |                        | 3095 mm  |                            |                      |                           | 3540 mm               |                            |
| Installation                               |                        | Rack mount   |                            |                      |                           |                       |                            |
| Motion range<br>(Maximum speed)<br>Note 1) | J1 axis rotation       | 370°(105°/s)   | 6.46 rad (1.83 rad/s)      | 370°(115°/s)         | 6.46 rad (2.01 rad/s)     | 370°(120°/s)          | 6.46 rad (2.09 rad/s)      |
|  | J2 axis rotation       | 200°(100°/s)   | 3.49 rad (1.75 rad/s)      | 200°(110°/s)         | 3.49 rad (1.92 rad/s)     | 200°(100°/s)          | 3.49 rad (1.75 rad/s)      |
|  | J3 axis rotation       | 375°(110°/s)   | 6.54 rad (1.92 rad/s)      | 375°(125°/s)         | 6.54 rad (2.18 rad/s)     | 375°(115°/s)          | 6.54 rad (2.01 rad/s)      |
|  | J4 axis wrist rotation | 720°(140°/s)   | 12.57 rad (2.44 rad/s)     | 720°(180°/s)         | 12.57 rad (3.14 rad/s)    | 720°(140°/s)          | 12.57 rad (2.44 rad/s)     |
|  | J5 axis wrist swing    | 250°(140°/s)   | 4.36 rad (2.44 rad/s)      | 250°(180°/s)         | 4.36 rad (3.14 rad/s)     | 250°(140°/s)          | 4.36 rad (2.44 rad/s)      |
|  | J6 axis wrist rotation | 720°(220°/s)   | 12.57 rad (3.84 rad/s)     | 720°(260°/s)         | 12.57 rad (4.54 rad/s)    | 720°(210°/s)          | 12.57 rad (3.66 rad/s)     |
| Max. load capacity at wrist                |                        | 210 kg   |                            | 165 kg               |                           | 100 kg                |                            |
| Max. load capacity at J2 base              |                        | 550 kg   |                            | 550 kg               |                           | 550 kg                |                            |
| Max. load capacity on J3 arm               |                        | 30 kg (A)  | (A)×4/3+(B) ≤ 40 kg        | 25 kg (C)            | (C) + (D) ≤ 50 kg         | 25 kg (E)             | (E)×2 + (F) ≤ 50kg         |
| Max. load capacity on J3 casing            |                        | 40 kg (B)  |                            | 50 kg (D)            |                           | 50 kg (F)             |                            |
| Allowable load moment at wrist             | J4 axis                | 1360 N·m   | 139 kgf·m                  | 940 N·m              | 96 kgf·m                  | 1000 N·m              | 102 kgf·m                  |
|  | J5 axis                | 1360 N·m   | 139 kgf·m                  | 940 N·m              | 96 kgf·m                  | 1000 N·m              | 102 kgf·m                  |
|  | J6 axis                | 735 N·m  | 75 kgf·m                   | 490 N·m              | 50 kgf·m                  | 706 N·m               | 72 kgf·m                   |
| Allowable load inertia at wrist            | J4 axis                | 147 kg·m <sup>2</sup>  | 1500 kgf·cm·s <sup>2</sup> | 89 kg·m <sup>2</sup> | 908 kgf·cm·s <sup>2</sup> | 227 kg·m <sup>2</sup> | 2316 kgf·cm·s <sup>2</sup> |
|  | J5 axis                | 147 kg·m <sup>2</sup>  | 1500 kgf·cm·s <sup>2</sup> | 89 kg·m <sup>2</sup> | 908 kgf·cm·s <sup>2</sup> | 227 kg·m <sup>2</sup> | 2316 kgf·cm·s <sup>2</sup> |
|  | J6 axis                | 82 kg·m <sup>2</sup>   | 837 kgf·cm·s <sup>2</sup>  | 46 kg·m <sup>2</sup> | 469 kgf·cm·s <sup>2</sup> | 196 kg·m <sup>2</sup> | 2000 kgf·cm·s <sup>2</sup> |
| Drive method                               |                        | Electric servo drive by AC servo motor   |                            |                      |                           |                       |                            |
| Repeatability Note 2)                      |                        | ±0.05 mm   |                            |                      |                           |                       |                            |
| Mass Note 3)                               |                        | 1370 kg  |                            |                      |                           | 1470 kg               |                            |
| Installation environment                   |                        | Ambient temperature : 0 to 45°C<br>Ambient humidity : Normally 75 %RH or less (No dew, nor frost allowed)<br>Short term Max. 95 %RH or less (within one month)<br>Vibration acceleration : 4.9 m/s <sup>2</sup> (0.5G) or less |                            |                      |                           |                       |                            |

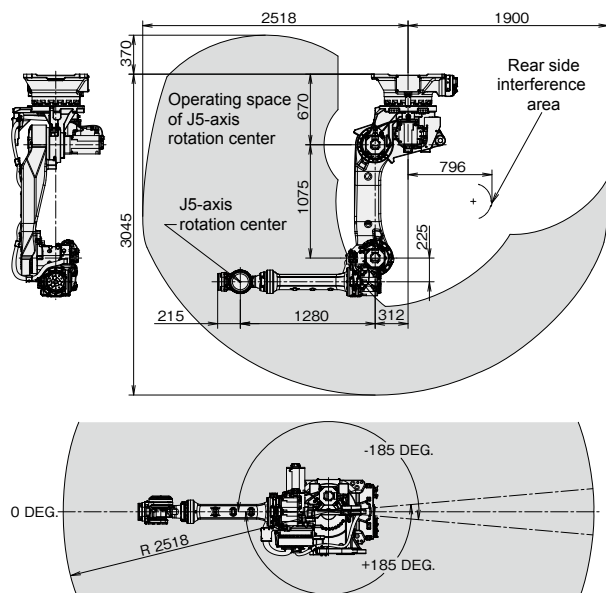
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

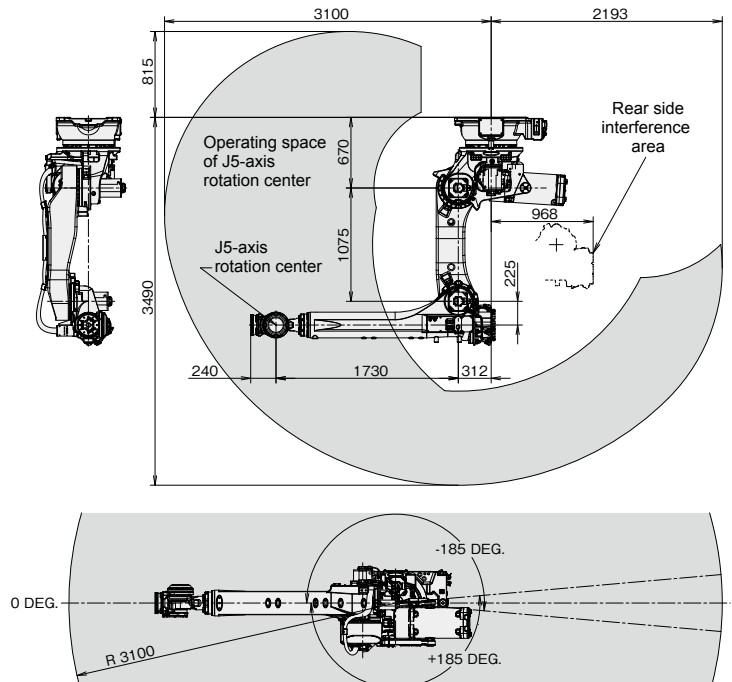
Note 3) Without controller.

## Operating space

### R-2000iC/220U



### R-2000iC/190U



## Specifications

| Model                                      |                        | R-2000iC/220U  |                        | R-2000iC/190U                                    |                        |
|--|------------------------|--|------------------------|--|------------------------|
| Type                                       |                        | Articulated Type   |                        |  |                        |
| Controlled axes                            |                        | 6 axes (J1, J2, J3, J4, J5, J6)  |                        |  |                        |
| Reach                                      |                        | 2518 mm  |                        | 3100 mm  |                        |
| Installation                               |                        | Upside-down  |                        |  |                        |
| Motion range<br>(Maximum speed)<br>Note 1) | J1 axis rotation       | 370°(120°/s)   | 6.46 rad (2.09 rad/s)  | 370°(105°/s)                                     | 6.46 rad (1.83 rad/s)  |
|  | J2 axis rotation       | 136°( 85°/s)   | 2.37 rad (1.48 rad/s)  | 136°( 85°/s)                                     | 2.37 rad (1.48 rad/s)  |
|  | J3 axis rotation       | 312°(110°/s)   | 5.45 rad (1.92 rad/s)  | 301°( 85°/s)                                     | 5.25 rad (1.48 rad/s)  |
|  | J4 axis wrist rotation | 720°(140°/s)   | 12.57 rad (2.44 rad/s) | 720°(120°/s)                                     | 12.57 rad (2.09 rad/s) |
|  | J5 axis wrist swing    | 250°(140°/s)   | 4.36 rad (2.44 rad/s)  | 250°(120°/s)                                     | 4.36 rad (2.09 rad/s)  |
|  | J6 axis wrist rotation | 720°(220°/s)   | 12.57 rad (3.84 rad/s) | 720°(200°/s)                                     | 12.57 rad (3.49 rad/s) |
| Max. load capacity at wrist                |                        | 220 kg   |                        | 190 kg   |                        |
| Max. load capacity at J2 base              |                        | -  |                        |  |                        |
| Max. load capacity on J3 arm               |                        | 25 kg (A)  | (A)×6/5 + (B) ≤ 30kg   | 20 kg (C)  | (C)×5/2 + (D) ≤ 50kg   |
| Max. load capacity on J3 casing            |                        | 30 kg (B)  |                        | 50 kg (D)  |                        |
| Allowable load moment at wrist             | J4 axis                | 1360 N·m 139 kgf·m   |                        | 1700 N·m 173 kgf·m                               |                        |
|  | J5 axis                | 1360 N·m 139 kgf·m   |                        | 1700 N·m 173 kgf·m                               |                        |
|  | J6 axis                | 735 N·m 75 kgf·m   |                        | 900 N·m 92 kgf·m                                 |                        |
| Allowable load inertia at wrist            | J4 axis                | 147 kg·m <sup>2</sup> 1500 kgf·cm·s <sup>2</sup>   |                        | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup> |                        |
|  | J5 axis                | 147 kg·m <sup>2</sup> 1500 kgf·cm·s <sup>2</sup>   |                        | 320 kg·m <sup>2</sup> 3265 kgf·cm·s <sup>2</sup> |                        |
|  | J6 axis                | 82 kg·m <sup>2</sup> 837 kgf·cm·s <sup>2</sup>   |                        | 230 kg·m <sup>2</sup> 2347 kgf·cm·s <sup>2</sup> |                        |
| Drive method                               |                        | Electric servo drive by AC servo motor   |                        |  |                        |
| Repeatability Note 2)                      |                        | ± 0.05 mm  |                        |  |                        |
| Mass Note 3)                               |                        | 1020 kg  |                        | 1400 kg  |                        |
| Installation environment                   |                        | Ambient temperature : 0 to 45°C<br>Ambient humidity : Normally 75 %RH or less (No dew, nor frost allowed)<br>Short term Max. 95 %RH or less (within one month)<br>Vibration acceleration : 4.9 m/s <sup>2</sup> (0.5G) or less |                        |  |                        |

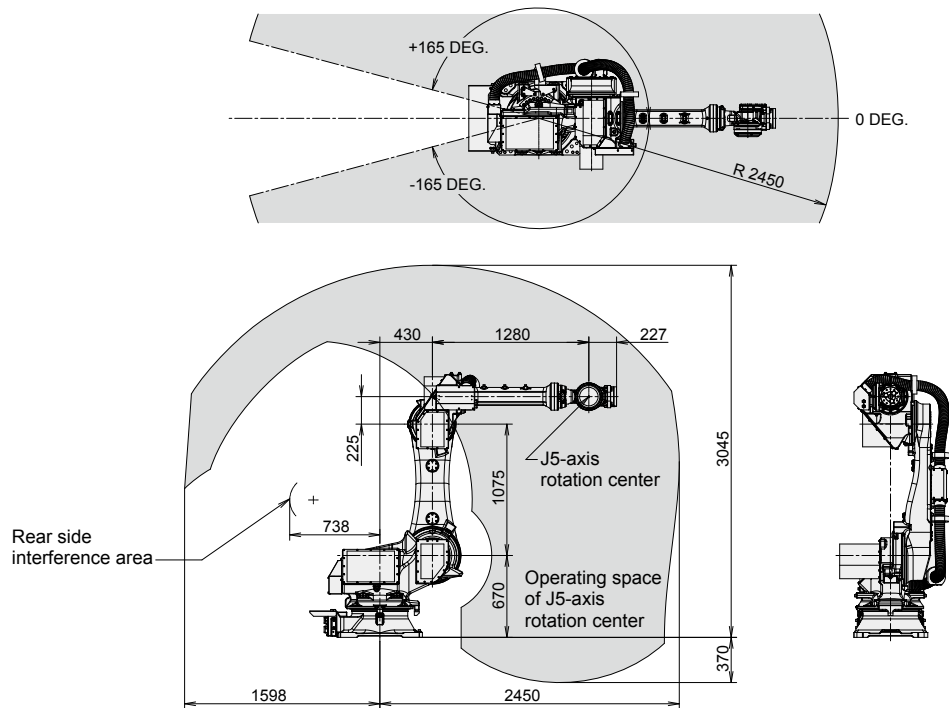
Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

## Operating space

# R-2000iC/210WE



## Specifications

| Model                                      |                        | R-2000iC/210WE  |                            |
|--|------------------------|---|----------------------------|
| Type                                       |                        | Articulated Type  |                            |
| Controlled axes                            |                        | 6 axes (J1, J2, J3, J4, J5, J6)   |                            |
| Reach                                      |                        | 2450 mm   |                            |
| Installation                               |                        | Rack mount  |                            |
| Motion range<br>(Maximum speed)<br>Note 1) | J1 axis rotation       | 330°( 95°/s)  | 5.76 rad (1.66 rad/s)      |
|  | J2 axis rotation       | 141°( 85°/s)  | 2.46 rad (1.48 rad/s)      |
|  | J3 axis rotation       | 318°( 95°/s)  | 5.55 rad (1.66 rad/s)      |
|  | J4 axis wrist rotation | 720°(120°/s)  | 12.57 rad (2.09 rad/s)     |
|  | J5 axis wrist swing    | 250°(120°/s)  | 4.36 rad (2.09 rad/s)      |
|  | J6 axis wrist rotation | 720°(190°/s)  | 12.57 rad (3.32 rad/s)     |
| Max. load capacity at wrist                |                        | 210 kg  |                            |
| Max. load capacity at J2 base              |                        | 550 kg  |                            |
| Max. load capacity on J3 arm               |                        | -   |                            |
| Max. load capacity on J3 casing            |                        | 10 kg   |                            |
| Allowable load<br>moment at wrist          | J4 axis                | 1333 N·m  | 136 kgf·m                  |
|  | J5 axis                | 1333 N·m  | 136 kgf·m                  |
|  | J6 axis                | 706 N·m   | 72 kgf·m                   |
| Allowable load<br>inertia at wrist         | J4 axis                | 141.1 kg·m <sup>2</sup>   | 1440 kgf·cm·s <sup>2</sup> |
|  | J5 axis                | 141.1 kg·m <sup>2</sup>   | 1440 kgf·cm·s <sup>2</sup> |
|  | J6 axis                | 78.4 kg·m <sup>2</sup>  | 800 kgf·cm·s <sup>2</sup>  |
| Drive method                               |                        | Electric servo drive by AC servo motor  |                            |
| Repeatability Note 2)                      |                        | ± 0.1 mm  |                            |
| Mass Note 3)                               |                        | 1180 kg   |                            |
| Installation environment                   |                        | Ambient temperature : 0 to 45°C<br>Vibration acceleration : 4.9 m/s <sup>2</sup> (0.5G) or less |                            |

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

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