FANUC Robot M-4101B, M-4101C



FEATURES

- M-410*i*B and M-410*i*C are palletizing robots which contribute to the robotization of the palletizing system.
- Suitable robot models can be selected according to the work pieces.

M-410 i B/140H	Payload 140kg
M-410 i B/700	Payload 700kg
M-410 <i>i</i> C/110	Payload 110kg
M-410 <i>i</i> C/185	Payload 185kg
M-410 i C/315	Payload 315kg
M-410 <i>i</i> C/500	Payload 500kg

- \bullet M-410 \dot{i} C/110 has a compact body and a high throughput.
- \bullet M-410iC/185, /315 and /500 support two types of base.

Pedestal type base:

The controller can be placed under the pedestal. It eliminates cabling at installation and saves the installation space.

Compact base:

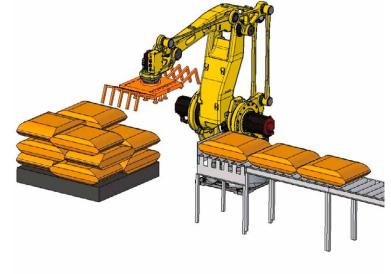
The base minimizes the robot maximum height. It is suitable for low ceiling location or for integrating into a manufacturing system.

- M-410iB/700, M-410iC/185, /315, /500 have the hollow wrist that enables easy wiring to a gripper.
- Advanced intelligent functions are available as an option, such as iRVision (integrated vision).

Application Examples



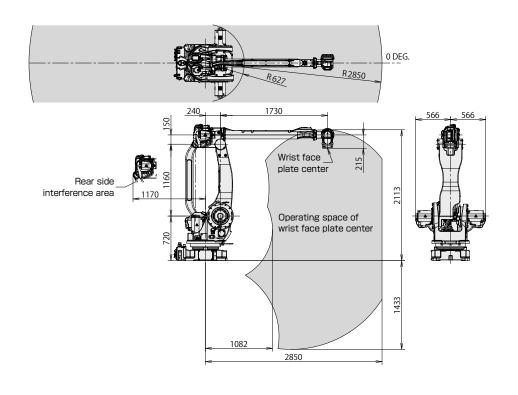
Boxes Palletizing

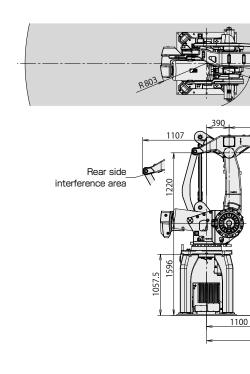


Bags Palletizing

M-410iB/140H

M-410i





Specifications

Model		M-410 <i>i</i> B/140H	
Type		Articulated Type	
Controlled axes		5 axes (J1, J2, J3, J4, J5)	
Reach		2850 mm	
Installation		Floor	
	J1 axis rotation	360° (140°/s)	
		6.28 rad (2.44 rad/s)	
	J2 axis rotation	155° (115°/s)	
Motion rongo		2.71 rad (2.01 rad/s)	
Motion range	10	112° (135°/s)	
(Maximum speed)	J3 axis rotation	1.95 rad (2.36 rad/s)	
Note 1)	J4 axis wrist	20° (135°/s)	
	swing Note 2)	0.35 rad (2.36 rad/s)	
	J5 axis wrist	720° (420°/s)	
	rotation	12.57 rad (7.33 rad/s)	
Max. load capacity at wrist		140 kg	
Max. load capacity on J2 base		550 kg	
Max. load capacity on J3 arm Note 3)		140 kg	
Allowable load J4 axis		147 kg·m ² 1500 kgf·cm·s ²	
inertia at wrist J5 axis		53 kg·m ² 540 kgf·cm·s ²	
Drive method		Electric servo drive by AC servo motor	
Repeatability Note 4)		± 0.05 mm	
Mass Note 5)		1200 kg	
Installation environment		Ambient temperature: 0 to 45°C	
		Ambient humidity: Normally 75%RH or less	
		(No dew, nor frost allowed)	
		Short term Max. 95%RH or less	
		(within one month)	
		Vibration acceleration: 4.9 m/s² (0.5G) or less	

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) The wrist interface is always toward to down ward. The angle is variable up to 20 degrees width.

Note 3) Max. load capacity on J3 arm depends on the load at wrist.

Note 4) Compliant with ISO 9283.

Note 5) Without controller.

Specifications

Model		
Type		
Controlled axes		
Reach		
Installation		
Motion range (Maximum speed) Note 1)	J1 axis rotation	
	J2 axis rotation	
	J3 axis rotation	
	J4 axis rotation	
Max. load capacity at wrist		
Allowable load inertia at wrist		
Drive method		
Repeatability No	ote 2)	
Mass Note 3)		
Installation environment		Ambien Ambien
		Vibratio

Note 1) During short distance motions, the axis

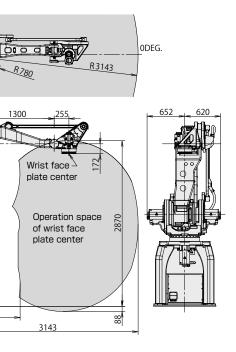
Note 2) Compliant with ISO 9283.

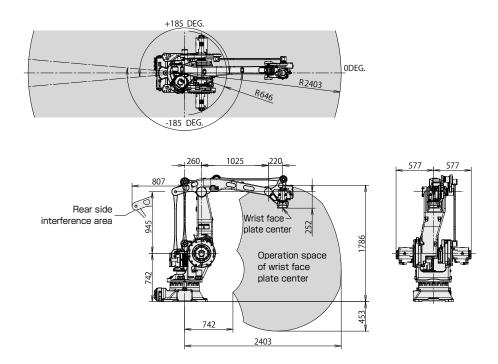
Note 3) Controller mass (120kg) is included.

Operating Space

B/700

M-410iC/110





M-410 <i>i</i> B/700
Articulated Type
4 axes (J1, J2, J3, J4)
3143 mm
Floor
360° (60°/s)
6.28 rad (1.05 rad/s)
144° (60°/s)
2.51 rad (1.05 rad/s)
136° (60°/s)
2.37 rad (1.05 rad/s)
540° (120°/s)
9.42 rad (2.09 rad/s)
700 kg
490 kg·m ² 5000 kgf·cm·s ²
Electric servo drive by AC servo motor
\pm 0.05 mm
2700 kg
t temperature : 0 to 45°C
t humidity: Normally 75%RH or less
(No dew, nor frost allowed)
Short term Max. 95%RH or less
(within one month)
n acceleration: 4.9 m/s² (0.5G) or less
speed may not reach the maximum value stated.

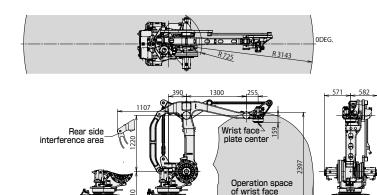
Specifications

Model		M-410 <i>i</i> C/110	
Type		Articulated Type	
Controlled axes		4 axes (J1, J2, J3, J4)	
Reach		2403 mm	
Installation		Floor	
	J1 axis rotation	370° (145°/s)	
		6.46 rad (2.53 rad/s)	
Motion rongo	J2 axis rotation	125° (130°/s)	
Motion range (Maximum speed)		2.18 rad (2.27 rad/s)	
Note 1)	12 avic rotation	140° (140°/s)	
Note 1)	J3 axis rotation	2.44 rad (2.44 rad/s)	
	J4 axis wrist rotation	720° (420°/s)	
		12.57 rad (7.33 rad/s)	
Max. load capacity at wrist		110 kg	
Max. load capacity on J2 base		550 kg	
Max. load capacity on J3 arm Note 2)		30 kg	
Allowable load in	ertia at wrist	53 kg·m² 540 kgf·cm·s²	
Drive method		Electric servo drive by AC servo motor	
Repeatability Note 3)		\pm 0.05 mm	
Mass		1030 kg Note 4)	
Installation environment		Ambient temperature: 0 to 45°C Ambient humidity: Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration: 4.9 m/s² (0.5G) or less	

- Note 1) During short distance motions, the axis speed may not reach the maximum value stated.
- Note 2) Max. load capacity on J3 arm depends on the load at wrist.
- Note 3) Compliant with ISO 9283.
- Note 4) Controller mass (120kg) is not included.

M-410iC/185,/315

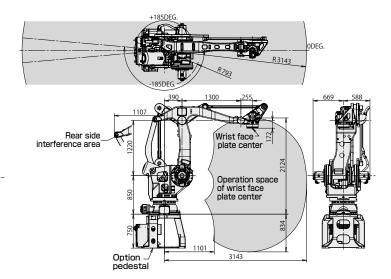
M-410iC/500



1100

plate center

3143



Specifications

Compact base

> Pedestal type base

•					
Model		del	M-4101 C/185	M-4101 C/315	
Type	Type		Articulat	Articulated Type	
Controll	ed axe	es	4 axes (J1,	4 axes (J1, J2, J3, J4)	
Reach			3143	3 mm	
Installat	ion		Floor		
		J1 axis	360° (140°/s)	360° (90°/s)	
		rotation	6.28 rad (2.44 rad/s)	6.28 rad (1.57 rad/s)	
Motion r	ange	J2 axis	144° (140°/s)	144° (100°/s)	
(Maximum	_	rotation	2.51 rad (2.44 rad/s)	2.51 rad (1.75 rad/s)	
Note 1		J3 axis	136° (140°/s)	136° (110°/s)	
I NOTE 1,	,	rotation	2.37 rad (2.44 rad/s)	2.37 rad (1.92 rad/s)	
		J4 axis	720° (305°/s)	720° (195°/s)	
		wrist rotation	12.57 rad (5.32 rad/s)	12.57 rad (3.40 rad/s)	
Max. load capacity at wrist		acity at wrist	185 kg	315 kg	
Max. load capacity on J2 base		city on J2 base	550 kg		
Max. load capacity on J3 arm Note 2)		on J3 arm Note 2)	30 kg		
Allowable load inertia		d inertia	88 kg·m²	155 kg•m²	
at wrist	at wrist		898 kgf·cm·s²	1580 kgf·cm·s ²	
Drive method			Electric servo drive by AC servo motor		
Repeatability Note 3)		Note 3)	± 0.05 mm		
Mass Pede	estal type	1600 kg Note 4)			
No pe		edestal	1330 kg Note 5)		
Installation environment			Ambient temperature : 0 to 45°C		
			Ambient humidity: Normally 75%RH or less		
		vironmont	(No dew, nor frost allowed)		
		WIIOHIHEHL	Short term Max. 95%RH		
			or less (within one month)		
			Vibration acceleration: 4.9 m/s² (0.5G) or less		

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Max. load capacity on J3 arm depends on the load at wrist.

Note 3) Compliant with ISO 9283. Note 4) Controller mass (120kg) is included. Note 5) Controller mass (120kg) is not included.

Specifications

Model		el	M-410 <i>i</i> C/500	
Type			Articulated Type	
Contro	lled axe	s	4 axes (J1, J2, J3, J4)	
Reach			3143 mm	
Installa	ition		Floor	
		J1 axis rotation	370° (85°/s) 6.46 rad (1.48 rad/s)	
Motion	_	J2 axis rotation	144° (85°/s)	
(Maximum speed) Note 1)	J3 axis	2.51 rad (1.48 rad/s) 136° (85°/s) 2.37 rad (1.48 rad/s)		
		J4 axis wrist rotation	720° (200°/s) 12.57 rad (3.49 rad/s)	
Max. load capacity at wrist			500 kg	
Max. load capacity at whist			550 kg	
Max. load capacity on J3 arm Note 2)			30 kg	
Allowable load inertia at wrist		l inertia	250 kg·m² 2550 kgf·cm·s²	
Drive method			Electric servo drive by AC servo motor	
Repeatability Note 3)		Note 3)	± 0.05 mm	
Macc ———	estal type	2410 kg Note 4)		
	edestal	1910 kg Note 5)		
Installation environment		vironment	Ambient temperature: 0 to 45°C Ambient humidity: Normally 75%RH or less (No dew, nor frost allowed) Short term Max. 95%RH or less (within one month) Vibration acceleration: 4.9 m/s² (0.5G) or less	

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Max. load capacity on J3 arm depends on the load at wrist.

Note 3) Compliant with ISO 9283. Note 4) Controller mass (120kg) is included. Note 5) Controller mass (120kg) is not included.

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